

# Reproducible neural network simulations: model validation on the level of network activity data

This poster summarizes [5,6].

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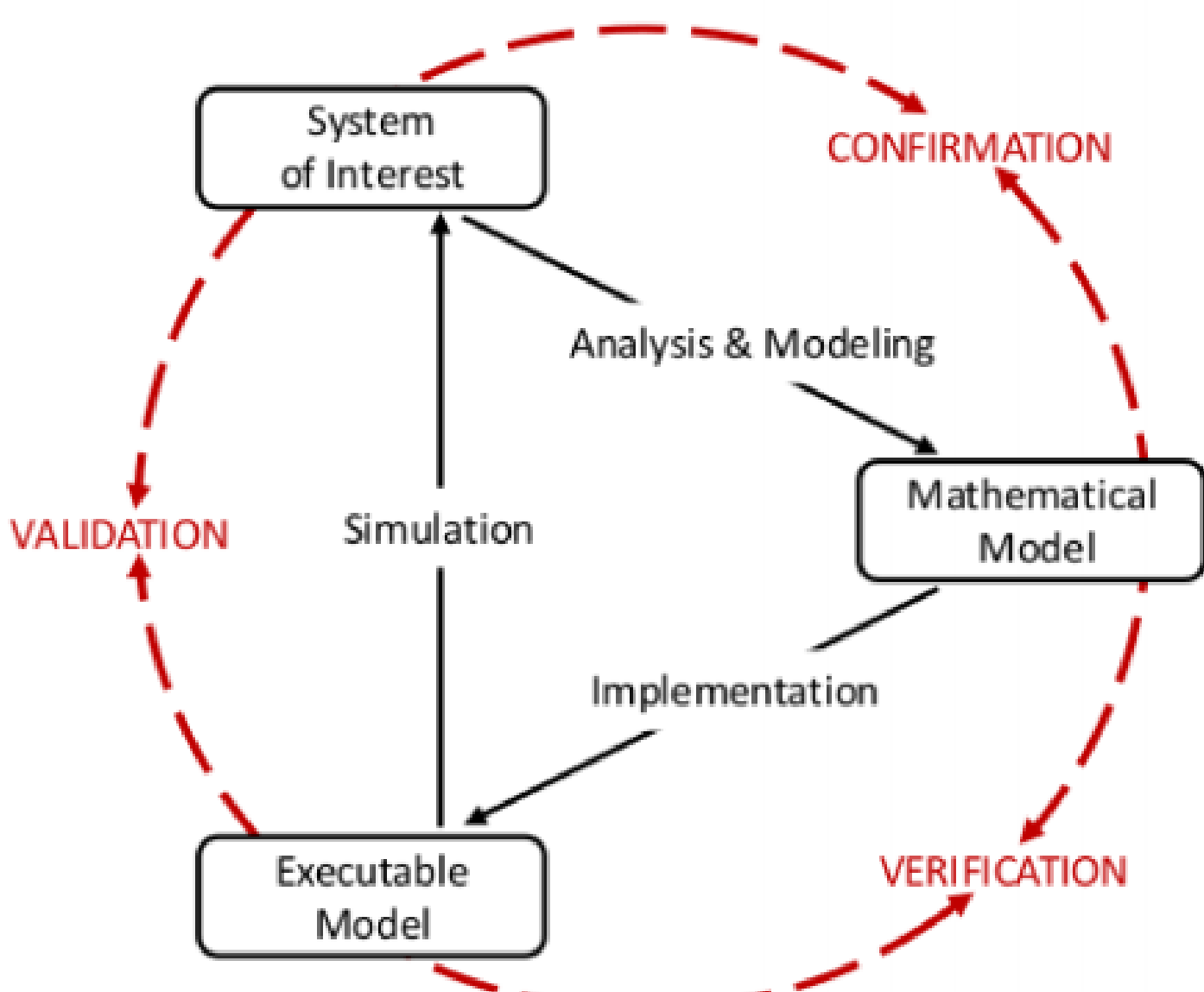
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## Concept

A model has the purpose to describe and predict its **system of interest**, which is a well defined entity selected for analysis. The model can be separated into two parts. The **mathematical model** is an abstract description formed by analysis and observation. The **executable model** is the implementation of the mathematical model which can perform simulations and thus generate testable predictions. [1][2]



Adapted from [1,2]

**Confirmation:** Assesses the plausibility of modeling choices and premises.

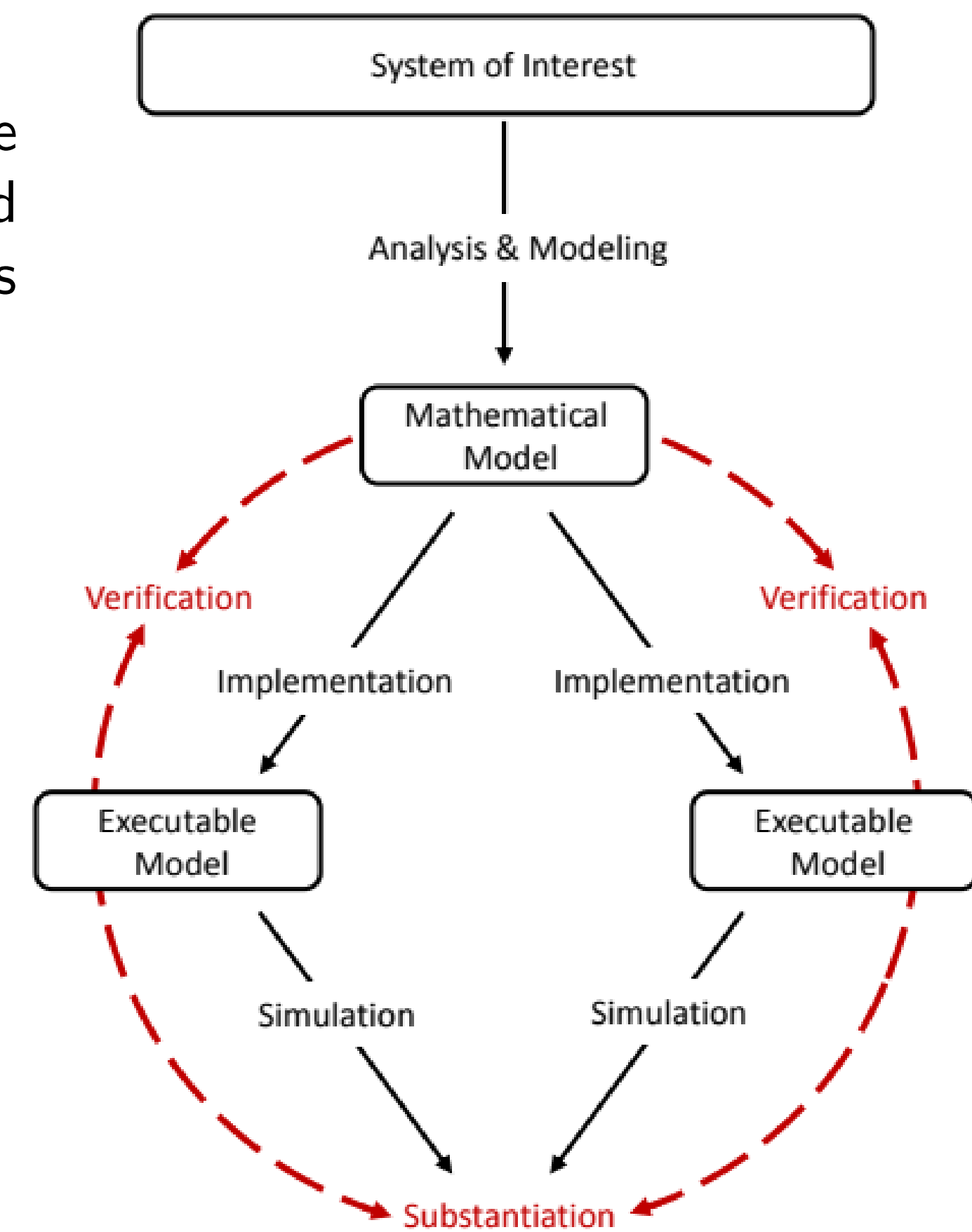
**Verification:** Ensures that the implementation is a correct representation of the mathematical model, concerning the code and the calculations.

**Validation:** Establishes confidence in the model by testing whether its prediction accuracy is within an acceptable agreement to the system of interest.

**Substantiation:** Defined here as the evaluation and quantifying the level of agreement between two executable models.

*In practice the substantiation performs equivalent tests as a validation and differs only in its interpretation.*

**Validation approach:** We validate by evaluating the simulation outcome on the **level of the network activity**, as opposed to the complementary approach of validating on a **single-cell level**.



## Model & Implementations

### Mathematical Model

**polychronization network model:** (Izhikevich [3])  
800 exc. / 200 inh. spiking neurons  
random connectivity, out-degree 100, random input,  
integer delays, trained with STDP, measured without STDP

Implementation

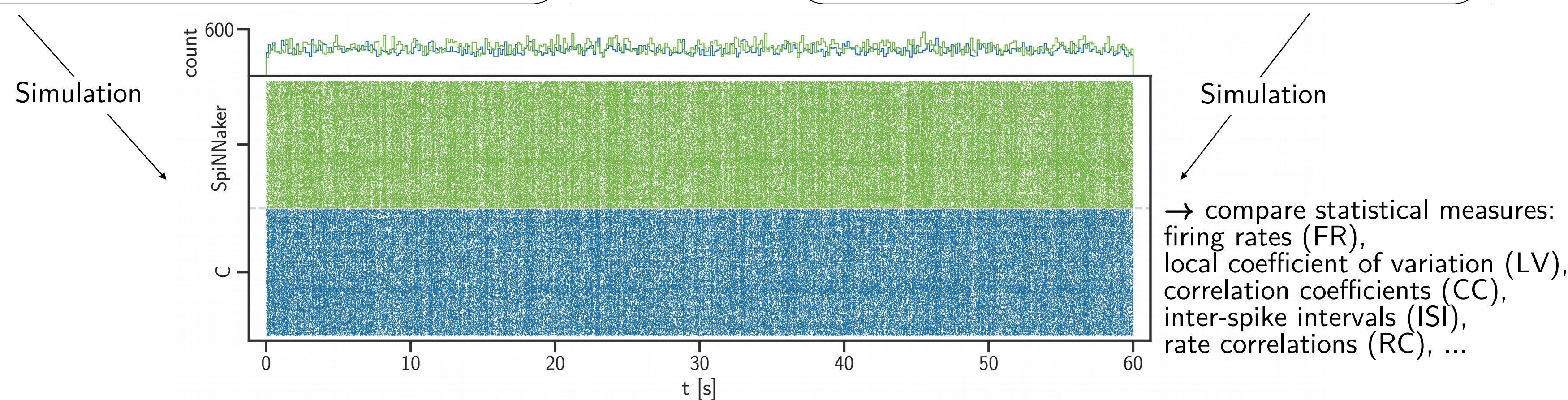
Implementation

### Executable Model

**custom C code:**  
original publication [3], refactored,  
adapted to make it transferable to SpiNNaker,  
1ms time steps

### Executable Model

**SpiNNaker neuromorphic system:** [4]  
brain-inspired digital computer architecture,  
uses fixed point representation of variables [5]  
3 iterative stages of the implementation (I,II,III)



## Python Validation Framework

developed at [github.com/INM-6/NetworkUnit](https://github.com/INM-6/NetworkUnit)

We developed the module **NetworkUnit** as a formalized Validation test framework based on *Elephant* [7] and *SciUnit* [8] for validation and substantiation in experiment and simulation.

```
import networkunit as newt
import sciunit

class polychronization_model(sciunit.Model, newt.capabilities.ProducesSpiketrains):
    def load(): # loads simulation outcome
        # ...

class C_model(polychronization_model):
    file_path = './simulation_data/C/'

class SpiNNaker_model(polychronization_model):
    file_path = './simulation_data/SpiNNaker/'

C = C_model()
S = SpiNNaker_model()

class rate_test(sciunit.TestM2M, newt.tests.firing_rate_test):
    score_type = newt.scores.effect_size # equips the test with a score

FR_test = rate_test()

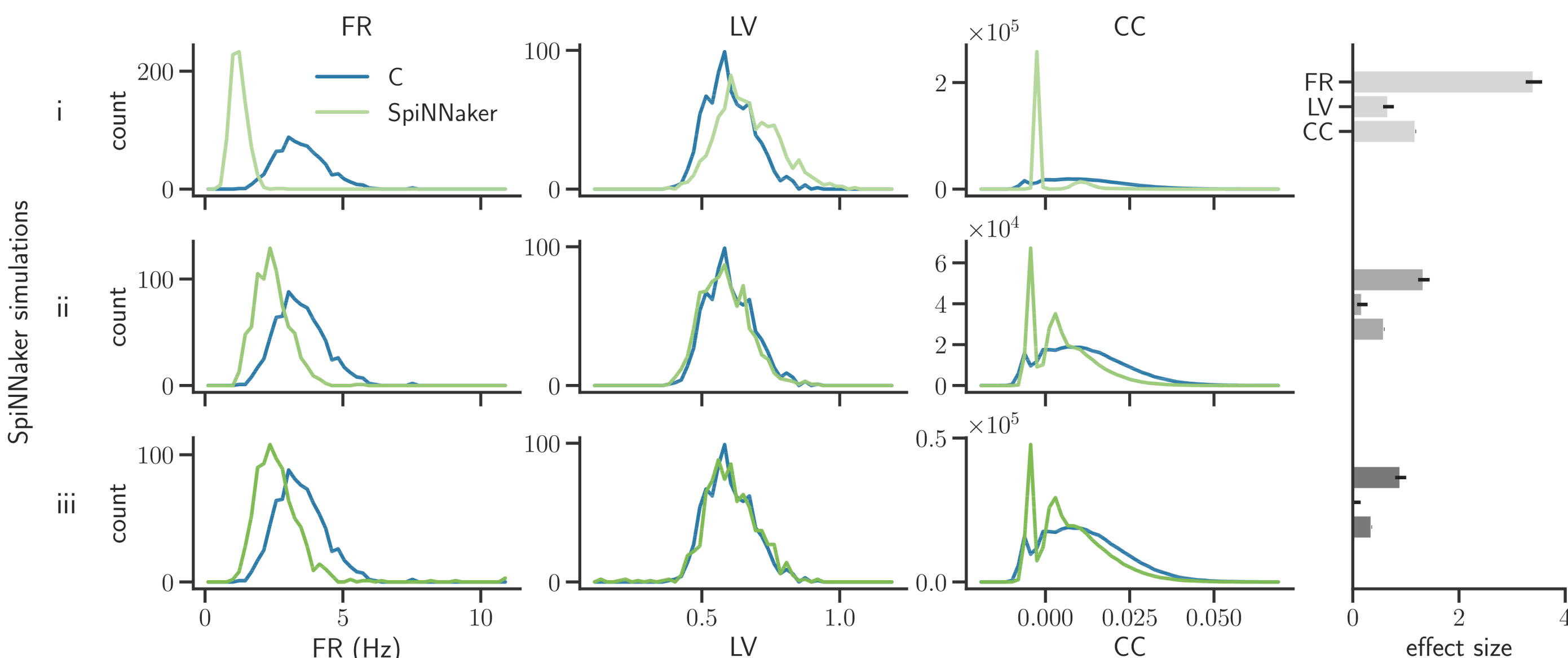
FR_test.judge([C,S]) # performs the validation test
```

**Effect Size**  
datasize: 800 800  
Effect Size = 0.394 CI = (0.295, 0.493)

## Substantiation by Iterative Validation Test Cycles (I, II, III)

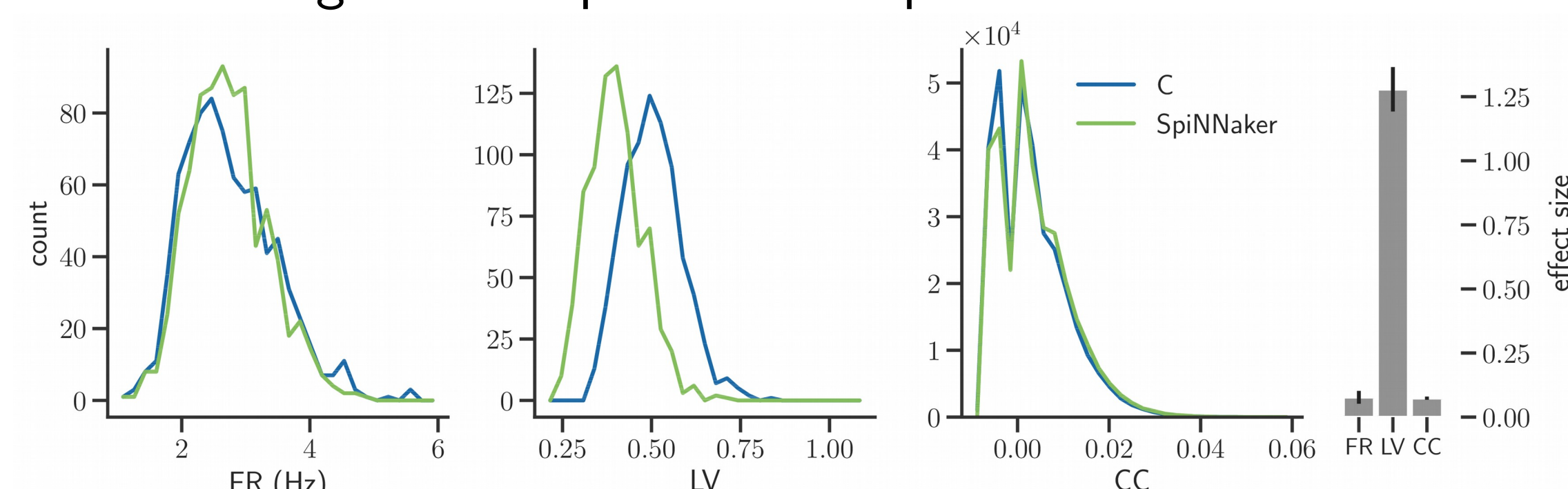
data, simulation code, and analysis code published at [web.gin.g-node.org/INM-6/network\\_validation](https://web.gin.g-node.org/INM-6/network_validation)

**I)** (i) uses an ESR ODE-solver, (ii) adapts Izhikevich's neural dynamics algorithm, (iii) uses a more exact fixed step-size forward Euler ODE-solver.



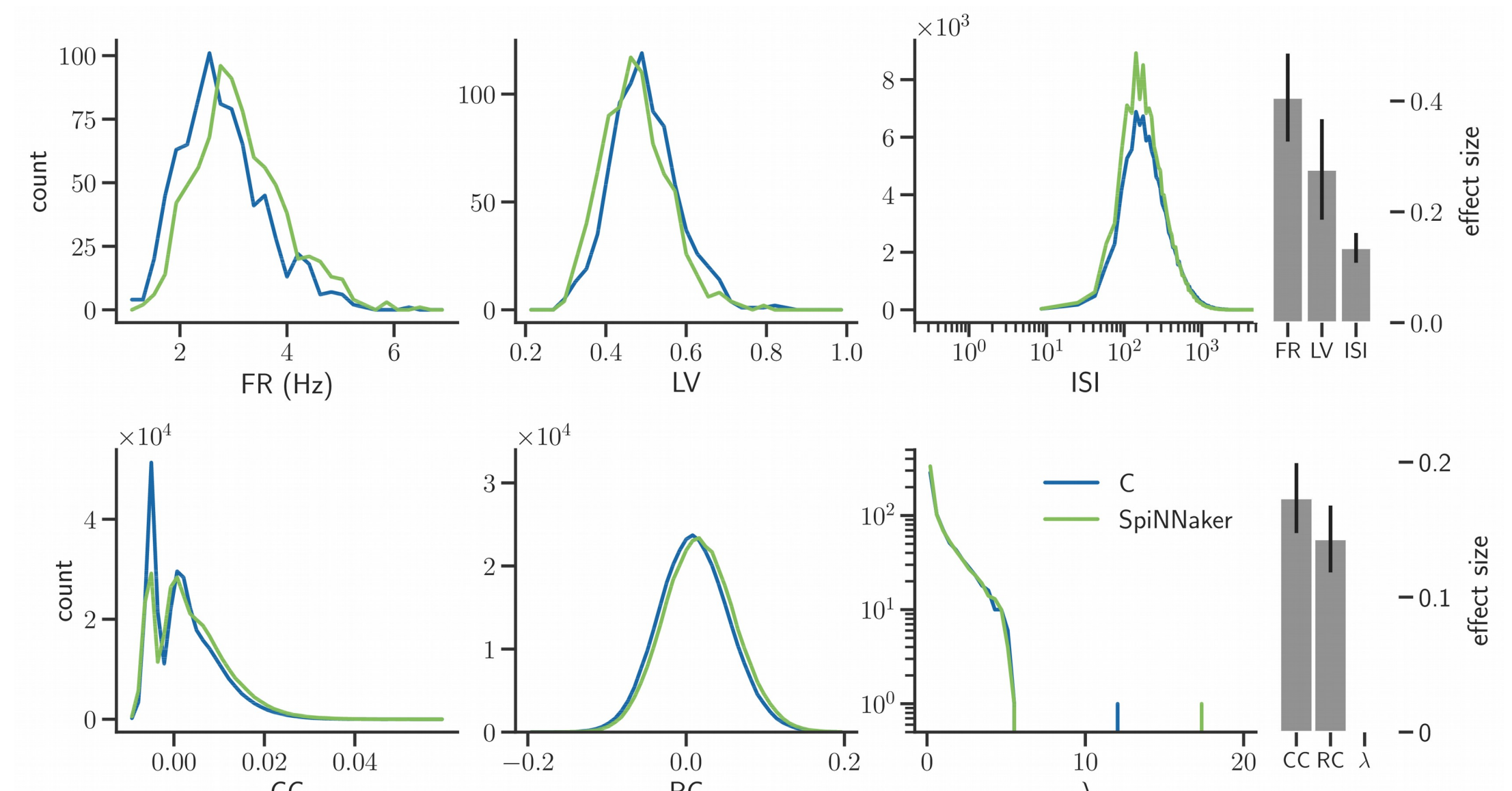
→ Validation results can guide model/implementation development.

**II)** uses finer integration steps and more precise detection of threshold crossing.

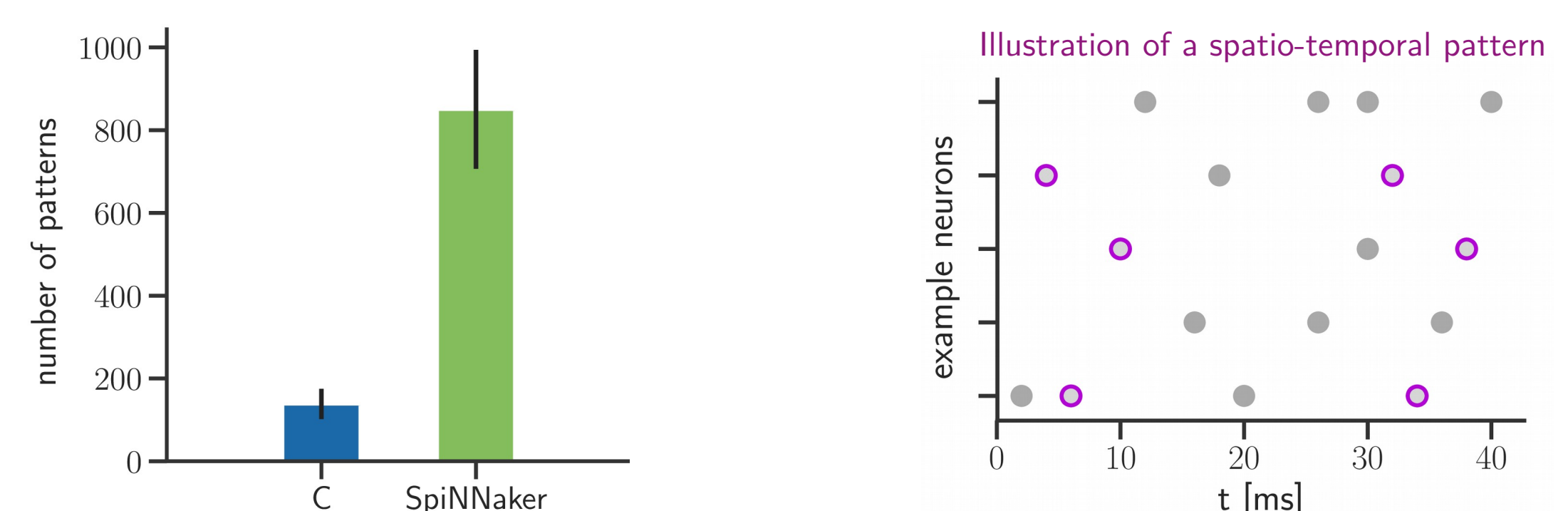


→ Agreement of complex measures does not entail agreement of simpler measures.

**III)** improves the threshold crossing detection algorithm on SpiNNaker.



→ Multiple measures are needed for a reasonable and comprehensive validation.



→ The evaluation of the level of agreement depends on the intended application. Here, despite good agreement of other measures, complex measures such as the pattern density (detected with SPADE [9]) is not yet consistent.

## References

[1] Schlesinger, S. (1979). *Terminology for model credibility*. Simulation 32, 103–104  
 [2] Thacker, B. et al. (2004) *Concepts of model verification and validation*. Tech. rep., Los Alamos National Lab  
 [3] Izhikevich, E. M. (2006) *Polychronization: Computation with spikes*, Neural Computation 18, 245–282  
 [4] Furber, S. et al. (2013) *Overview of the SpiNNaker system architecture*. IEEE Transactions on Computers 62  
 [5] Trenschi G. et al. (2018) *Rigorous neural network simulations: model cross-validation for boosting the correctness of simulation results*, under review in Frontiers of Neuroinformatics  
 [6] Gutzen R. et al (2018) *Reproducible neural network simulations: model validation on the level of network activity data*, under review in Frontiers of Neuroinformatics

[7] Electrophysiology Analysis Toolkit (python-elephant.org)  
 [8] SciUnit (scidash.github.io)  
 [9] Quaglio, P. et al. (2017) *Detection and evaluation of spatio-temporal spike patterns in massively parallel spike train data with SPADE*, Frontiers in Computational Neuroscience 11, 41

## Acknowledgments:

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